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Compactifications with S-duality Twists

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Nov 28, 2004 Wien Scherk-Schwarz (SS) Reductions are generalisations of Kaluza-Klein (KK) reductions [Scherk, Schwarz, 1979].

Theory must possess a <u>global symmetry</u>, G. The reduction ansatz is determined by the action of the symmetry on the fields.

-Introduces mass parameters

-Introduces a scalar potential

-Supersymmetry Breaking

-Moduli Fixing

-New massive/gauged SUGRA and corresponding string compactifications. (Related with flux compactifications in string theory) We generalise SS Reductions:

We use <u>S-duality</u> type symmetries for the reduction.

General meaning. A simple example is the electromagnetic duality of the Maxwell equations in the absence of source terms

$$E \to B, \qquad B \to -E$$

$$L \sim E^2 - B^2$$

Interchanges field equations and Bianchi identities

$$dF = 0, \qquad d \star F = 0$$

This is what we mean by S-duality:

 Acts through electromagnetic duality, interchanges field equations and Bianchi identity.

 Is a symmetry of the field equations, but not the action.

EXAMPLES

1) Heterotic String theory on T^6 : classical SL(2, R) symmetry:

Montonen-Olive type S-duality symmetry acting on the axion-dilaton fields

$$\tau = \chi + ie^{-\phi} \mapsto \frac{a\tau + b}{c\tau + d}, \quad g_s \mapsto \frac{1}{g_s}$$

strong-weak coupling duality. Symmetry of the field equations only.

2) D = 11 SUGRA on T^d : $E_{d,d}$. If D = 2n then a symmetry of the field equations only. e.g.

$$D = 4 \longrightarrow E_7$$

$$D = 6 \longrightarrow SO(5,5)$$

$$D = 8 \longrightarrow SL(3,R) \times SL(2,R)$$

Why important??

New gauged SUGRA
New compactifications:
S-folds (When lifted to string/M/F theory)

Why difficult??

With a symmetry of the field equations, the best we can do is to reduce the field equations... Messy!

STRATEGY

Implement symmetry at the level of an <u>"equivalent"</u> auxiliary Lagrangian and do the SS reduction on the action.

The auxiliary Lagrangian has extra degrees of freedom (dof). The number of dof is kept correct by imposing a self-duality equation.

what do we get?

-Calculations simplified

-Novel features: massive self-duality. CS terms.. Particularly interesting in $D = 4 \rightarrow D = 3$ [Nicolai-Samtleben, 2003]

OUTLINE

- 1. Scherk-Schwarz Mechanism
- 2. Doubled Formalism
- 3. Applications

Consider SS on S^1 : $D + 1 \rightarrow D$ (y, x^{μ}) : $S^1 \times M^D$. $y \sim y + 2\pi R$. $G : \Phi \mapsto g[\Phi]$ Scherk-Schwarz ansatz is $\Phi(x^{\mu}, y) = g(y)\Phi(x)$ $g : S^1 \longrightarrow G$, $g(y) = \exp[M\frac{y}{2\pi R}]$

MONODROMY: $\mathcal{M} = \Phi(x, 2\pi R) \Phi^{-1}(x, 0) = e^M \in G$

Classified by conjugacy classes of \mathcal{M} .

Mass matrix M determines the mass parameters, the gauge group and the scalar potential of the lower dimensional theory. G = SL(2, R): 3 conjugacy classes \Rightarrow 3 distinct reductions. The hyperbolic, elliptic and parabolic monodromy and mass matrices:

$$\mathcal{M}_{h} = \begin{pmatrix} e^{m} & 0\\ 0 & e^{-m} \end{pmatrix}, \ \mathcal{M}_{e} = \begin{pmatrix} \cos m & \sin m\\ -\sin m & \cos m \end{pmatrix},$$
$$\mathcal{M}_{p} = \begin{pmatrix} 1 & m\\ 0 & 1 \end{pmatrix}.$$

$$M_{h} = \begin{pmatrix} m & 0 \\ 0 & -m \end{pmatrix}, \quad M_{e} = \begin{pmatrix} 0 & m \\ -m & 0 \end{pmatrix},$$
$$M_{p} = \begin{pmatrix} 0 & m \\ 0 & 0 \end{pmatrix}$$

 M_e : compact gauging SO(2) M_h , M_p : SO(1,1)-gauged lower dimensional theories

Geometrical picture

 Φ are sections of $P(M^D \times S^1, G)$. Twist the fibers with $\mathcal{M} \Rightarrow$ non-trivial transition functions.

Useful picture to understand lifting to F/M/string theory. e.g. G = SL(2, R): Compactification on T^2 bundle over S^1 (τ modulus of T^2). -non-trivialisable due to the twist- Interesting when the transition functions are not geometric symmetries. Consistent non-geometric string backgrounds: T-folds, U-folds, S-folds. [Hull, 2004]

Parabolic: T-duality along one of the legs of T^2 : untwisted T^3 with H-flux \longrightarrow relation to flux compactifications.

SUGRA, scalars:G/H, H: maximal compact supgroup of G. r n-1 form fields A_{n-1}^i , $H_n^i = dA_{n-1}^i$:

$$\mathcal{L} = R * 1 + \frac{1}{4} \operatorname{tr}(d\mathcal{K} \wedge *d\mathcal{K}^{-1}) - \frac{1}{2} H_n^T \mathcal{K} \wedge *H_n$$
$$A \to L^{-1} A, \qquad \mathcal{K} \to L^T \mathcal{K} L$$

Scherk-Schwarz ansatz:

$$\hat{\mathcal{K}}(x,y) = \lambda^{T}(y)\mathcal{K}(x)\lambda(y)$$
$$\hat{A}_{n-1}(x,y) = \lambda^{-1}(y)[A_{n-1}(x) + A_{n-2}(x) \wedge dy].$$
$$\lambda(y) = e^{My}.$$

Scalar Potential comes from $\partial_y \mathcal{K}^{-1} \partial^y \mathcal{K}$:

$$V(\phi) = -\frac{1}{2}e^{2(D-1)\alpha\varphi}\operatorname{tr}(M^2 + M\mathcal{K}^{-1}M^T\mathcal{K}) * 1$$

Stable only when $\mathcal{M} \in H \longrightarrow$ Minkowski vacuum, no cosm. const., all SUSY is broken. Other \mathcal{M} give BPS domain wall solutions.

$$\hat{H}_{n}(x,y) = e^{-My} H_{n}(x) + e^{-My} H_{n-1}(x) \wedge (dy + \mathcal{A})$$
$$H_{n-1}(x) = dA_{n-2} - (-1)^{n-1} MA_{n-1},$$
$$H_{n}(x) = dA_{n-1} - H_{n-1} \wedge \mathcal{A}.$$

Kinetic term reduces as:

 $[e^{-2(n-1)\alpha\varphi}H_n^T \mathcal{K} \wedge *H_n + e^{2(D-n)\alpha\varphi}H_{n-1}^T \mathcal{K} \wedge *H_{n-1}]$ Stückelberg type symmetry:

 $\delta A_{n-1} = d\lambda, \qquad \delta A_{n-2} = (-1)^{n-1} M\lambda$ Can be used to set $A_{n-2} = 0$ by

$$A_{n-1} \to A_{n-1} + (-1)^{n-1} M^{-1} dA_{n-2}.$$

 $H_n = DA_{n-1} = dA_{n-1} - (-1)^n MA_{n-1} \wedge \mathcal{A}$

 $H_{n-1} = (-1)^n M A_{n-1}$ mass term

$$\delta \mathcal{A} = d\gamma, \quad \delta A_{n-1} = -\gamma M A_{n-1}$$

Gauge group generated by M. Gauge field \mathcal{A}

Doubled Formalism: [Cremmer, Julia, Lu, Pope, 1998]

$$\mathcal{L} = -\frac{1}{2}R_{ij}F_n^i \wedge *F_n^j - \frac{1}{2}S_{ij}F_n^i \wedge F_n^j + \mathsf{L}(\Phi)$$

D=2nk potential fields $A^i_{n-1}.~F=dA^i_{n-1}.$ Field Equations: $dG^i=0,~~G^i=\delta \mathcal{L}/\delta F^i$ Bianchi Identities: $dF^i=0$

Solve $dG^i = 0$ by introducing k dual potentials \tilde{A}^i_{n-1} (regarded as independent fields), $G = d\tilde{A}^i_{n-1}$

It is possible to construct a manifestly G-invariant Lagrangian $\mathcal{L}(A, \tilde{A})$. \ddagger dof is halved by imposing a self-duality constraint

$$H_n^i = J_j^i(\phi) * H_n^j \quad G-covariant$$

where

$$J^{i}_{\ j} = \Omega^{ik} \mathcal{K}_{kj}. \quad H_n = \left(\begin{array}{c} dA_{n-1} \\ d\tilde{A}_{n-1} \end{array} \right).$$

 Ω is the G invariant matrix. Note $(J*)^2 = 1$.

SS reduction of the constraint (in the fixed gauge):

$$DA_{n-1} = \tilde{M} * A_{n-1}$$

where $\tilde{M} \propto JM$. This is a massive self-duality condition in the odd D = 2n - 1 dimensions:

$$\Rightarrow *D * A_{n-1} \propto \tilde{M}^2 * A_{n-1}$$

Can be derived from a Chern-Simons action with mass term:

$$L = P_{ij}A^i \wedge DA^j + \hat{M}_{ij}A^i \wedge *A^j$$

where $\hat{M} = P\tilde{M}$, P_{ij} :constant matrix. Number of dof:

$$\begin{split} D &= 2n : \text{k massless } A_{n-1}^{I} = 2\text{k massless } A_{n-1}^{I}, \tilde{A}_{n-1}^{I} \\ &+ \text{ constraint } = \text{k}c_{n-1}^{2n-2} \\ D &= 2n-1 : \text{twisted: k massless } A_{n-1}^{I} + \text{k massless } A_{n-2}^{I} = \text{k}c_{n-1}^{2n-2} \\ &\text{less } A_{n-2}^{I} = \text{k}c_{n-1}^{2n-2} \\ &\text{untwisted: 2k massive } \\ A_{n-1}^{I} + \text{ constraint } = \text{k}c_{n-1}^{2n-2} \\ c_{p}^{s} &= s!/p!(s-p)!. \end{split}$$

D-DIMENSIONAL LAGRANGIAN:

$$\mathcal{L}_D = \mathcal{L}_g + \mathcal{L}_b + \mathcal{L}_s$$

$$\mathcal{L}_{g} = R * 1 - \frac{1}{2} d\varphi \wedge * d\varphi - \frac{1}{2} e^{-2(D-1)\alpha\varphi} \mathcal{F}_{2} \wedge * \mathcal{F}_{2}$$

$$\mathcal{L}_{s} = \frac{1}{4} \operatorname{tr}(\mathcal{D}\mathcal{K} \wedge * \mathcal{D}\mathcal{K}^{-1}) - \frac{1}{2} e^{2(D-1)\alpha\varphi} \operatorname{tr}(M^{2} + M\mathcal{K}^{-1}M^{T}\mathcal{K}) * 1$$

$$\mathcal{L}_{b} = \frac{1}{2} (\Omega^{-1}M)_{ij} [(-1)^{n-1}A_{n-1}^{(i)} \wedge DA_{n-1}^{(j)} + e^{2(D-n)\alpha\varphi} \tilde{M}_{k}^{j} A_{n-1}^{(i)} \wedge * A_{n-1}^{(k)}].$$

APPLICATIONS

D=8: Type IIB on T^2 or 11D on T^3 . The classical symmetries are U-duality: $SL(3,R) \times SL(2,R)_{\tau}$, τ : complex structure modulus

T-duality: $SL(2,R)_{\sigma} \times SL(2,R)_{\tau}$, σ : Kähler modulus, first factor is embedded in SL(3,R).

S-duality: $SL(2, R)_{\lambda}$, Inherited from S-duality of Type IIB in 10D. Subgroup of SL(3, R) and conjugate to $SL(2, R)_{\sigma}$.

Scalar fields parametrise:

$$\frac{SL(3,R)}{SO(3)} \times \frac{SL(2,R)}{SO(2)}$$

 (A_3, \tilde{A}_3) form an SL(2, R) doublet.

*We use $SL(2, R)_{\tau}$ to twist the reduction. Symmetry of field equations only and acts on 3-form potential fields through electromagnetic duality transfromations.

D=4

D=4 N=8 SUGRA

 E_7 duality symmetry of equations of motion. (A^I, \tilde{A}^I), $I = 1, \dots, 28$ transform under **56** of E_7 . 70 scalars: $E_7/SU(8)$.

D=4 N=4 SUGRA coupled to p vector multiplets:

$$O(6,p) \times SL(2,R)$$

 (A^{I}, \tilde{A}^{I}) $I = 1, \dots, 6+p$ form 6+p doublets A^{mI} transforming in the (**2**, **6+p**). Scalars:

 $SL(2,R)/SO(2) \times O(6,22)/O(6) \times O(22).$

$$H^{mI} = Q^m_n \mathcal{R}^I_J * H^{nJ}$$
$$J^m_n = \Omega^{mp} \mathcal{K}_{pn} \text{ and } \mathcal{R}^I_J = L^{IK} \mathcal{N}_{KJ}.$$
$$J = Q \otimes \mathcal{R}$$

D=6

D=6 N=8 SUGRA

SO(5,5) duality symmetry of field equations only. 5 -form fields and their duals form a **10** of SO(5,5). The 25 scalars parametrise

 $\frac{SO(5,5)}{SO(5)\times SO(5)}$

(A truncation) of Type IIB on T^6

 $SL(2,R)_{IIB} \times SL(2,R)_{EM}$